## MGBS

MGBS	Motor mounting option:
MGBS - 32 - 0802 - 200 - AB - AU - AA - AB - AA	
	Hotor mounting option:         - Leave blank: Without a motor         Mounting option:         - A: With a motor side drive MSD facing up         - B: With a motor side drive MSD facing up         - C: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: With a motor side drive MSD facing up         - D: Connectors facing up         - D: Connectors facing right         - D: Connectors facing left         - D: Connectors facing left         - D: Connectors facing left         - D: Connectors facing left
Motor type:         - A: Stepper motor without a brake         - B: Stepper motor with a brake         Motor size []:         - A: 28 mm (Currently not available)         - B: 42 mm         - C: 56 mm         - D: 86 mm (Currently not available)         Available sizes:         - MGBS 32: 28, 42         - MGBS 45: 42, 56         - MGBS 60: 56, 86	Lin combination with a motor side Up Right
	Drive option:         - Leave blank: Without a motor or drive         Drive type:         - A: Stepper         Drive-motor cables option:         - Leave blank: Without a motor or drive         - 00: Without the cables         Cables type:         - A: Robotic with a straight plug         - B: Robotic with an angled plug

- Leave blank: Without a motor or drive

Power cable: -

ROLLCO

- 0: Without a power cable

- A: With a power cable



#### pter VK own

Left



## drive MSD



Α

А

В

Α

Left

When using the motor side drive MSD, the connectors can not be facing the MGBS otherwise, the connectors and MGBS may collide. These combinations are: BD, CL, DU and ER.

## • Drive protocol/control: - A: EtherCAT

- B: Ethernet based communication
- C: Pulse-direction control
- D: Profinet



Α

## Cables length:

- A: 3 m B: 5 m
- C: 10 m

# Signal cable: - 0: Without a signal cable - A: With a signal cable